

Localizing Romans SUGRA

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Introduction

- Solving Einstein's equations is hard!
- But sometimes it is not necessary!
- Some AdS/CFT observables are just integrals over (sub-)spaces of spacetime.
- E.G. the on-shell action should give the large N index in field theory.

$$I \sim \int_M \text{vol}(M) (R + \dots)$$

- Looks very dependent on knowing the metric.....

Introduction

- Equivariant Localization gives a way to compute these without knowing the metric! [Benetti-Genolini, Gauntlett, Sparks]
- Rough Idea:
 - Spacetime with a symmetry.
 - Integrals only receive contributions from symmetry fixed points.

- $$\text{Obs} = \int_M \Phi = \sum_{\text{f.p.}} \Phi_0$$

Remarks:

- Don't need to know explicit solution.
- Result depends on topology.
- Uniform method for obtaining results.

Equivariant Localization

Equivariant Cohomology

- Interested in computing integrals over manifolds with a symmetry group.
- Consider a $2n$ -dimensional manifold without boundary.
- ξ a Killing vector field:

$$\mathcal{L}_\xi g = 0 \quad \Leftrightarrow \quad \nabla_\mu \xi_\nu + \nabla_\nu \xi_\mu = 0$$

- Assume that it generates a $U(1)$ isometry.
- We are interested in integrating forms, Φ which satisfy

$$\mathcal{L}_\xi \Phi = 0$$

Equivariant Cohomology

- We replace cohomology with equivariant cohomology.

- Exterior derivative replaced by twisted derivative

$$d \rightarrow d_\xi = d - \xi \lrcorner$$

- Forms are replaced by poly-forms, these are just forms of mixed degree.

$$\Phi = \Phi_n + \Phi_{n-2} + \dots + \Phi_0$$

- In general d_ξ is not nilpotent: $d_\xi^2 = -\mathcal{L}_\xi$

- Restrict to equivariant polyforms: $\mathcal{L}_\xi \Phi = 0$, then d_ξ is nilpotent.

Equivariant Cohomology

- Can define ξ -equivariant de Rham cohomology.
- Equivariantly closed if $d_\xi \Phi = 0$.

$$d\Phi_n = 0, \quad \xi \lrcorner \Phi_n = d\Phi_{n-2}, \quad \dots \quad \xi \lrcorner \Phi_2 = d\Phi_0$$

- Equivariantly exact if $\Phi = d_\xi \Psi$.
- n 'th ξ -equivariant cohomology group is

$$H_\xi^n(M) = \frac{\ker(d_\xi) \mid \Lambda_\xi^n(M)}{\text{Im}(d_\xi) \mid \Lambda_\xi^{n-1}(M)}$$

- For freely acting groups is ordinary cohomology on M/G .

Equivariant Cohomology

- Equivariant integrals over M are defined as integrals over the top form of equivariantly closed form Φ :

$$\int_M \Phi \equiv \int_M \Phi_{2n}$$

- Top form is closed but not exact.
- Can add an equivariantly exact poly-form without changing result.

$$\int_M (\Phi + d_\xi \Phi) = \int_M \Phi$$

- Integrals depend only on the equivariant cohomology class.

Equivariant integrals localise

- Integrals localise to fixed points of the symmetry.

$$M_\xi = \{x \in M \mid \xi|_x = 0\}$$

- We are free to modify intervals by equivariantly exact pieces.

$$\int_M \Phi = \int_M \Phi_t \equiv \int_M \Phi e^{t d_\xi \beta}$$

- Where β is some ξ -equivariant polyform: $\mathcal{L}_\xi \beta = 0$.

$$\frac{d}{dt} \Phi_t = \Phi(d_\xi \beta) e^{t d_\xi \beta} = d_\xi(\beta \wedge \Phi_t)$$

- Difference is equivariantly exact! Integrals are the same for all t .

Equivariant integrals localise

- For $t = 0$ we have the original integral, but we can evaluate for any t .
- If $d_\xi \beta|_{0\text{-form}}$ is semi-negative definite with maximum equal to 0 and we take $t \rightarrow \infty$ limit the integral localises to the minima.

- Take $\beta = \eta \equiv g(\xi, \bullet)$ then we have:

$$\int_M \Phi = \lim_{t \rightarrow \infty} \int_M \Phi e^{t d\eta} e^{-t|\xi|^2} = \lim_{t \rightarrow \infty} \int_M e^{-t|\xi|^2} \Phi \wedge \sum_k (t d\eta)^k \frac{1}{k!}$$

- The $e^{-t|\xi|^2}$ acts as a delta function onto M_ξ !

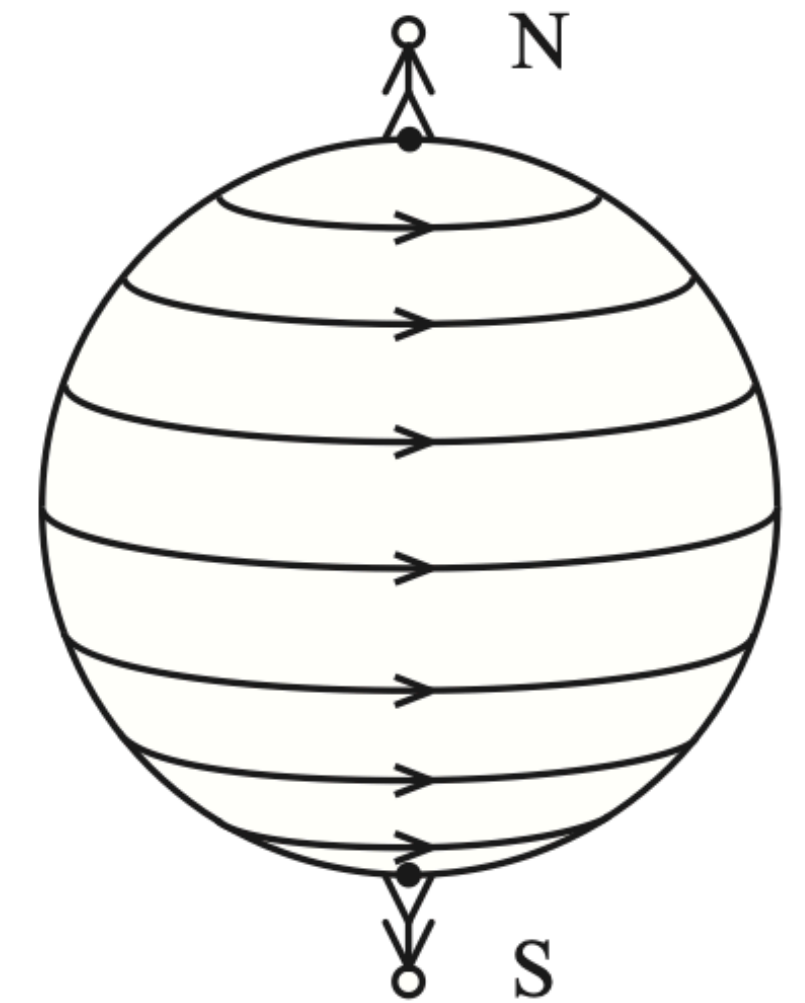
Isolated fixed points

- Integrals localise, but how do we compute the contributions?
- Assume the localisation locus M_ξ is a set of fixed points: $M_\xi = \{x_k\}$. E.g. S^2 .
- Zoom in near such a fixed point, p using Cartesian coordinates $x_i = r_i \cos \phi_i$, $y_i = r_i \sin \phi_i$ $i \in \{1, \dots, n\}$ with origin at p .
- Locally metric reads:

$$ds^2 \simeq \sum_{i=1}^n (dx_i^2 + dy_i^2) = \sum_{i=1}^n (dr_i^2 + r_i^2 d\phi_i^2)$$

- Killing vector takes the form

$$\xi \simeq \sum_{i=1}^n b_i^p \left(x_i \frac{\partial}{\partial y_i} - y_i \frac{\partial}{\partial x_i} \right) = \sum_{i=1}^n b_i^p \frac{\partial}{\partial \phi_i}$$



Isolated fixed points

- The circle action generated by ξ acts on the i 'th eigenspace as:

$$\begin{pmatrix} x_i \\ y_i \end{pmatrix} = \begin{pmatrix} \cos(b_i^p \phi_i) & \sin(b_i^p \phi_i) \\ -\sin(b_i^p \phi_i) & \cos(b_i^p \phi_i) \end{pmatrix} \begin{pmatrix} x_i \\ y_i \end{pmatrix}$$

- Can also compute η , for us $d_\xi \eta$ is locally given by:

$$d_\xi \eta \simeq \sum_{i=1}^n b_i^p d(r_i^2) \wedge d\phi_i - \sum_{i=1}^n (b_i^p)^2 r_i^2$$

- Remains to plug all this into the integral for Φ_t .

Isolated fixed points

- The final result is:

$$\lim_{t \rightarrow \infty} \int_{\mathcal{N}_p} \Phi_t = \lim_{t \rightarrow \infty} \Phi_0(p) \prod_{i=1}^n t b_i^p \int_0^{2\pi} d\phi_i \int_0^\infty dr_i^2 e^{-t(b_i^p)^2 r_i^2}$$

- This is just a Gaussian integral!

$$\int_{N_p} \Phi = \Phi_0(p) \frac{(2\pi)^n}{\prod_{i=1}^n b_i^p}$$

- We now just add up all the contributions from fixed points!

Beyond isolated fixed points

- One does not need to have just isolated fixed points.
- E.g. The Schwarzschild metric.

$$ds^2 = -f(r)dt^2 + f(r)^{-1}dr^2 + r^2 ds^2(S^2)$$

- At the horizon $f(r_h) = 0$ and it locally looks like

$$ds^2 \simeq ds^2(\mathbb{R}^{1,1}) + r_h^2 ds^2(S^2)$$

- The Killing vector $\xi = \partial_t$ has a *bolt* at the horizon. A whole S^2 is fixed by the action.
- Need to take into account other fixed point loci.
- Can have fixed point sets of dimension 0,2,4,....

BVAB theorem

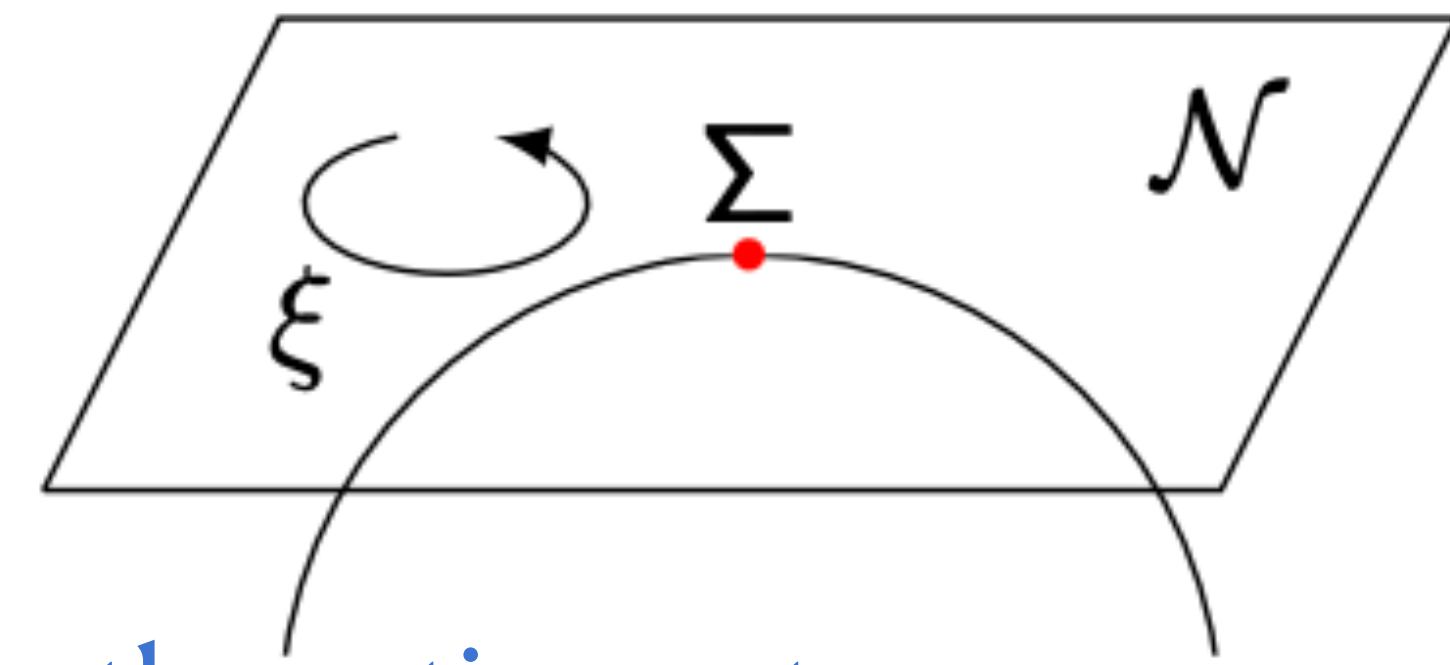
- Can apply a similar logic to work out these contributions, result is the
- **BVAB theorem:** [Berline, Vergne 82, Atiyah, Bott 84].

The integral of an equivariantly closed form localises to fixed points of symmetry.

The diagram illustrates the BVAB theorem formula:
$$\int_M \Phi = \sum_{\Sigma} \int_{\Sigma} \frac{f^* \Phi}{e_{\xi}(\mathcal{N})}$$
 It features three callout boxes: 1. A blue box on the left pointing to the integral over M containing the text "What we care about". 2. A blue box at the bottom pointing to the summation over Σ containing the text "Sum over fixed point set". 3. Two blue boxes on the right pointing to the fraction: the top one contains "Pullback to Σ of Φ " and the bottom one contains "Euler form of normal bundle".

- This looks a bit scary but it is not.

BVAB Theorem



- What is a fixed point set?

- What is the normal bundle?

- $e_\xi(\mathcal{N})$?

- Somewhere where the action acts trivially, $\xi = 0$ there.

- Bundle of points normal to fixed point

set: $\mathcal{N} = \sum_{i=1}^k \mathcal{L}_i \cong \mathbb{R}^{2k}$

- The Euler class of the normal bundle.

$$e(\xi)(\mathcal{N}) = \prod_{i=1}^k \left[c_1(\mathcal{L})_i + \frac{\epsilon_i}{2\pi} \right]$$

First Chern class

Weights of action

BVAB

The full gory details:

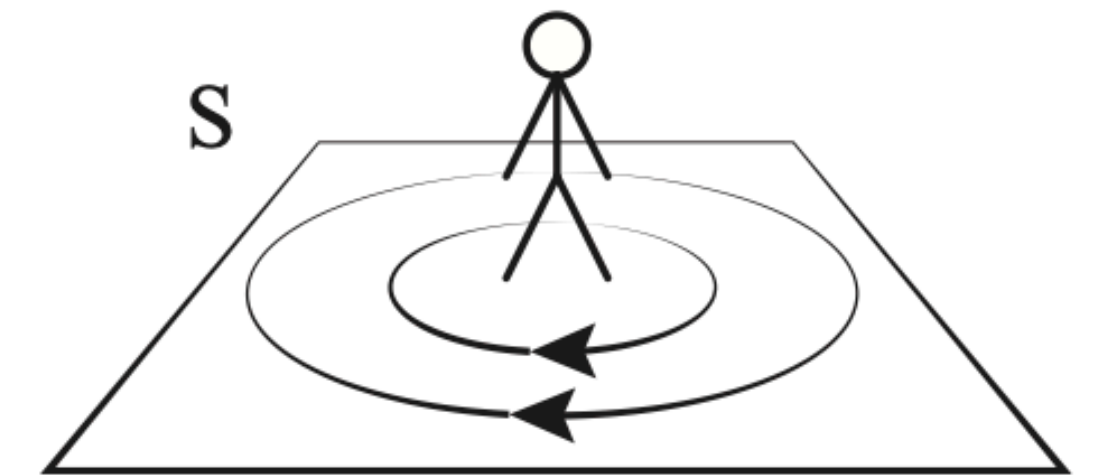
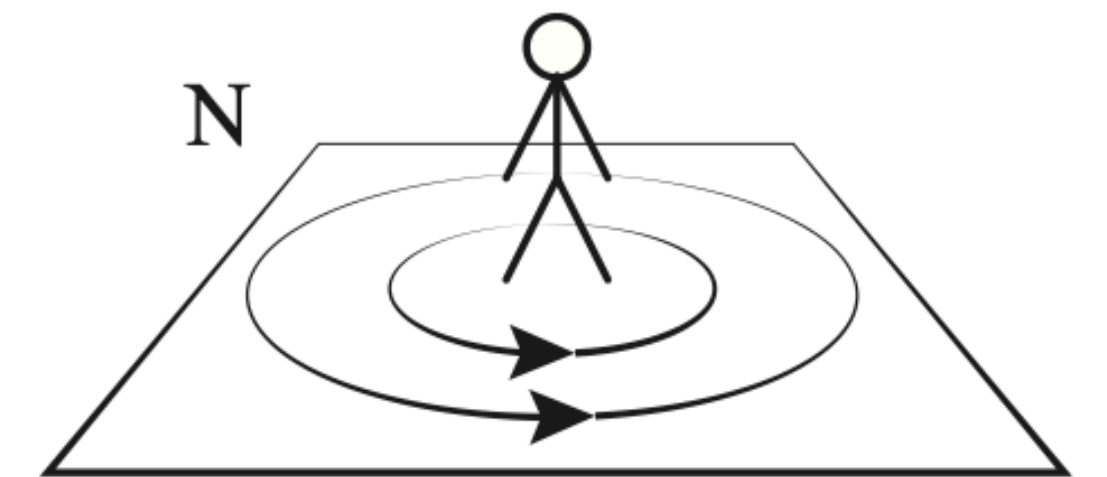
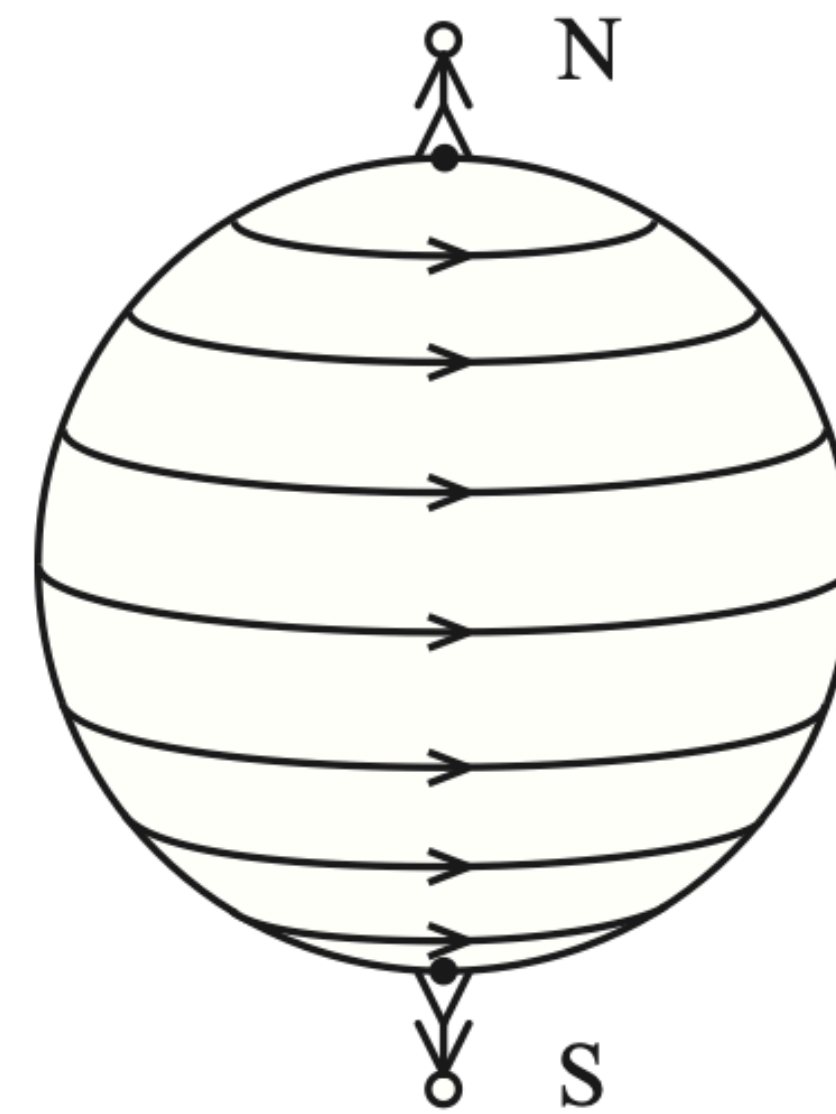


$$\begin{aligned}
 \int_{M_{2n}} \Phi &= \sum_{\Sigma} \frac{(2\pi)^k}{\prod_{i=1}^k \epsilon_i} \int_{\Sigma} \frac{f^* \Phi}{\prod_{i=1}^k \left[1 + \frac{2\pi}{\epsilon_i} c_1(\mathcal{L}_i) \right]} \\
 &= \sum_{\dim_0} \frac{1}{d_{F_0}} \frac{(2\pi)^n}{\epsilon_1 \cdots \epsilon_n} \Phi_0 + \sum_{\dim_2} \frac{1}{d_{F_2}} \frac{(2\pi)^{n-1}}{\epsilon_1 \cdots \epsilon_{n-1}} \int \left[\Phi_2 - \Phi_0 \sum_{1 \leq i \leq n-1} \frac{2\pi}{\epsilon_i} c_1(\mathcal{L}_i) \right] \\
 &+ \sum_{\dim_4} \frac{1}{d_{F_4}} \frac{(2\pi)^{n-2}}{\epsilon_1 \cdots \epsilon_{n-2}} \int \left[\Phi_4 - \Phi_2 \wedge \sum_{1 \leq i \leq n-2} \frac{2\pi}{\epsilon_i} c_1(\mathcal{L}_i) + \Phi_0 \sum_{1 \leq i \leq j \leq n-2} \frac{(2\pi)^2}{\epsilon_i \epsilon_j} c_1(\mathcal{L}_i) \wedge c_1(\mathcal{L}_j) \right] + \cdots
 \end{aligned}$$

S^2 example

- $ds^2 = d\theta^2 + \sin^2 \theta d\phi^2$
- $\text{Vol} = \int_{S^2} \sin \theta d\theta \wedge d\phi \equiv \int_{S^2} \Phi$
- $\xi = \partial_\phi$. Need polyform:
- $\xi \lrcorner \Phi_2 = d\Phi_0 = d \cos \theta$.
- Two fixed points at poles of sphere.
- $\text{Vol} = \frac{2\pi}{\epsilon_N} \Phi_0|_N + \frac{2\pi}{\epsilon_S} \Phi_0|_S$
 $= 2\pi(\cos(0) - \cos(\pi)) = 4\pi$ ✓

This is cheating a bit, we know the metric.
This is a problem with the example.

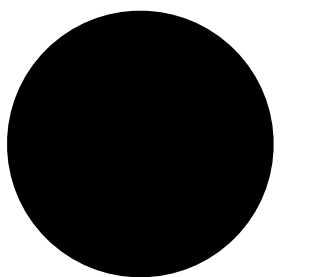


$\mathbb{C}\mathbb{P}^2$ Example

- Consider the metric

$$ds^2 = d\zeta^2 + \frac{1}{4} \sin^2 \zeta \cos^2 \zeta (d\psi + \cos \theta d\phi)^2 + \frac{1}{4} \sin^2 \zeta (d\theta^2 + \sin^2 \theta d\phi^2)$$

- Choice of Killing vector $\xi = b_1 \partial_\psi + b_2 \partial_\phi$. Different types of fixed point sets!
- For ∂_ψ fixed point at $\zeta = 0$ and bolt at $\zeta = \frac{\pi}{2}$.
- For ∂_ϕ , 3 fixed points at $(\zeta = 0)$, $(\zeta = \frac{\pi}{2}, \theta = 0)$ and $(\zeta = \frac{\pi}{2}, \theta = \pi)$.
- Polyforms different and different types of fixed point locus but give same results!



(Useful) Applications

Romans SUGRA

Euclidean Romans SUGRA

- 6d gauged supergravity theory.
- Bosonic content: metric, dilaton X , $SU(2)$ gauge fields + 2-form potential.
- Preserve supersymmetry, need to solve Killing spinor equations $\nabla_\mu \epsilon + \dots = 0$.
- Places constraints on metric and fields. “Torsion conditions” from spinor bilinears:
 $P = -\bar{\epsilon}\gamma_7\epsilon$. [Alday, Fluder, Gregory, Richmond, Sparks]
- Implies existence of a Killing vector ξ + conditions like $d(XP) = -\frac{1}{\sqrt{2}}\xi \lrcorner F$.
- Construct Polyforms using torsion conditions, e.g. $\Phi^F = F - \sqrt{2}XP$.

Fixed points

- What are the possible fixed points?

$$F = \{\xi = 0\} \subset M_6$$

- Even dimensional sub manifolds of M_6

$$F = F_0 \cup F_2 \cup F_4$$

- On fixed point set the Killing spinor is chiral! $\epsilon|_F = \epsilon_{\pm}$.
- In fact it is stronger:

$$-i\gamma^{(2i-1)(2i)}\epsilon = \sigma^{(i)}\epsilon, \quad \sigma^{(i)} = \pm 1$$

Master formula

$$\begin{aligned}
 I = & \frac{F_{S^5}}{27} \left[\sum_{\text{dim} 0} \chi \frac{(\sigma^{(1)}\epsilon_1 + \sigma^{(2)}\epsilon_2 + \sigma^{(3)}\epsilon_3)^3}{\epsilon_1\epsilon_2\epsilon_3} \right. \\
 & - \sum_{\text{dim} 2} \frac{\chi(\sigma^{(1)}\epsilon_1 + \sigma^{(2)}\epsilon_2)^2}{\epsilon_1\epsilon_2} \int_{F_2} \left[3c_1(F) + (\sigma^{(1)}\epsilon_1 + \sigma^{(2)}\epsilon_2) \left(\frac{c_1(L_1)}{\epsilon_1} + \frac{c_1(L_2)}{\epsilon_2} \right) \right] \\
 & \left. + \sum_{\text{dim} 4} \chi \sigma^{(1)} \int_{F_4} \left[3c_1(F) \wedge c_1(F) + 3\sigma^{(1)}c_1(F) \wedge c_1(L_1) + c_1(L_1) \wedge c_1(L_1) \right] \right]
 \end{aligned}$$

- $\sigma^{(1)}\sigma^{(2)}\sigma^{(3)} = \chi$
- The on-shell action for **any** solution is given by the above!
- Need to specify the weights, σ 's and $c_1(L)$'s.

Some technical stuff

- There are also conditions for the spinor to be well defined that one needs to impose. For two-dim fixed point set

$$\int_{\Sigma_g} c_1(F) = \sigma^{(1)} \int_{\Sigma_g} c_1(L_1) + \sigma^{(2)} \int_{\Sigma_g} c_1(L_2) - \sigma^{(3)} \chi(\Sigma_g)$$

- Imposes the type of twist to preserve supersymmetry e.g a “topological twist”.
- Similar condition for four-dim fixed point set but more complicated.

$$2\eta\chi(B_4) + 3\tau(B_4) = \int_{B_4} \left(\sigma^{(1)} c_1(L_1) + c_1(F) \right)^2$$

- Plug into on-shell action. For dim 0 and dim 2 purely topological result. For dim 4 need information about magnetic charges.

Example 1

5d SCFTs on a Riemann surface

- Take $M_6 = \mathbb{R}^4 \times \Sigma_g$.
- Conformal boundary is $S_b^3 \times \Sigma_g$.
- Dual to twisted compactification of 5d SCFTs on Σ_g , placed on squashed S_b^3 .
- Write $\mathbb{R}^4 = \mathbb{R}^2 \oplus \mathbb{R}^2$ with ∂_{ϕ_i} rotating the two copies, take $c_1(L_i) = 0$.
- Take $\xi = b_1 \partial_{\phi_1} + b_2 \partial_{\phi_2}$. Fixed point set: $F_2 = \Sigma_g$ at centre of \mathbb{R}^4 .

Plug everything in!

$$\begin{aligned}
I = & \frac{F_{S^5}}{27} \left[\sum_{\dim 0} \gamma \frac{(\sigma^{(1)}\epsilon_1 + \sigma^{(2)}\epsilon_2 + \sigma^{(3)}\epsilon_3)^3}{\epsilon_1\epsilon_2\epsilon_3} \right. \\
& - \sum_{\dim 2} \frac{\chi(\sigma^{(1)}\epsilon_1 + \sigma^{(2)}\epsilon_2)^2}{\epsilon_1\epsilon_2} \int_{F_2} \left[3c_1(F) + (\sigma^{(1)}\epsilon_1 + \sigma^{(2)}\epsilon_2) \left(\frac{c_1(L_1)}{\epsilon_1} + \frac{c_1(L_2)}{\epsilon_2} \right) \right] \\
& + \sum_{\dim 4} \chi\sigma^{(1)} \int_{F_4} \left[3c_1(F) \wedge c_1(F) + 3\sigma^{(1)}\epsilon_1(F) \wedge c_1(L_1) + c_1(L_1) \wedge c_1(L_1) \right]
\end{aligned}$$

$$\epsilon_i = b_i$$

$$\int_{\Sigma_g} c_1(F) = \sigma^{(1)} \int_{\Sigma_g} c_1(L_1) + \sigma^{(2)} \int_{\Sigma_g} c_1(L_2) - \sigma^{(3)} \chi(\Sigma_g)$$

Example 1

5d SCFTs on a Riemann surface

$$I = \frac{F_{S^5}}{9} \chi(\Sigma_g) \sigma^{(1)} \sigma^{(2)} \frac{(b_1 + \sigma^{(1)} \sigma^{(2)} b_2)^2}{b_1 b_2}$$

- Matches field theory results!
- Easy in the end, just plugging things into the master formula.
- No solving equations of motion!

Example 2

Black saddle

- $M_6 = \mathbb{R}^2 \times B_4$ “Schwarzschild like solution” a.k.a Black Saddle
- Conformal boundary is $S^1 \times B_4$.
- Dual to 5d SCFT on B_4 .
- $\xi = b\partial_\phi$ with ∂_ϕ rotating \mathbb{R}^2
- Fixed point set $F = B_4$ at centre of \mathbb{R}^2 . Set $c_1(L) = 0$ again.

Plug everything in!

$$\begin{aligned}
I = & \frac{F_{S^5}}{27} \left[\sum_{\dim 0} \frac{\chi (\sigma^{(1)}\epsilon_1 + \sigma^{(2)}\epsilon_2 + \sigma^{(3)}\epsilon_3)^3}{\epsilon_1\epsilon_2\epsilon_3} \right. \\
& - \sum_{\dim 2} \frac{\chi (\sigma^{(1)}\epsilon_1 + \sigma^{(2)}\epsilon_2)^2}{\epsilon_1\epsilon_2} \int_{F_2} \left[3c_1(F) + (\sigma^{(1)}\epsilon_1 + \sigma^{(2)}\epsilon_2) \left(\frac{c_1(L_1)}{\epsilon_1} + \frac{c_1(L_2)}{\epsilon_2} \right) \right] \\
& + \sum_{\dim 4} \chi \sigma^{(1)} \int_{F_4} \left[3c_1(F) \wedge c_1(F) + 3\sigma^{(1)} c_1(F) \wedge c_1(L_1) + c_1(L_1) \wedge c_1(L_1) \right]
\end{aligned}$$

$$2\eta\chi(B_4) + 3\tau(B_4) = \int_{B_4} (\sigma^{(1)}c_1(L_1) + c_1(F))^2$$

Example 2

Black saddle

$$I = \frac{F_{S^5}}{9} (2\chi(B_4) + 3\eta\tau(B_4))$$

- For any choice of B_4 . Result is purely topological!
- Result not noticed before.
- To compare with literature let $B_4 = \Sigma_{g_1} \times \Sigma_{g_2}$.
- $\tau(\Sigma_{g_1} \times \Sigma_{g_2}) = 0$ and $\chi(\Sigma_{g_1} \times \Sigma_{g_2}) = \chi(\Sigma_{g_1})\chi(\Sigma_{g_2})$

$$I = \frac{8F_{S^5}}{9} (1 - g_1)(1 - g_2)$$

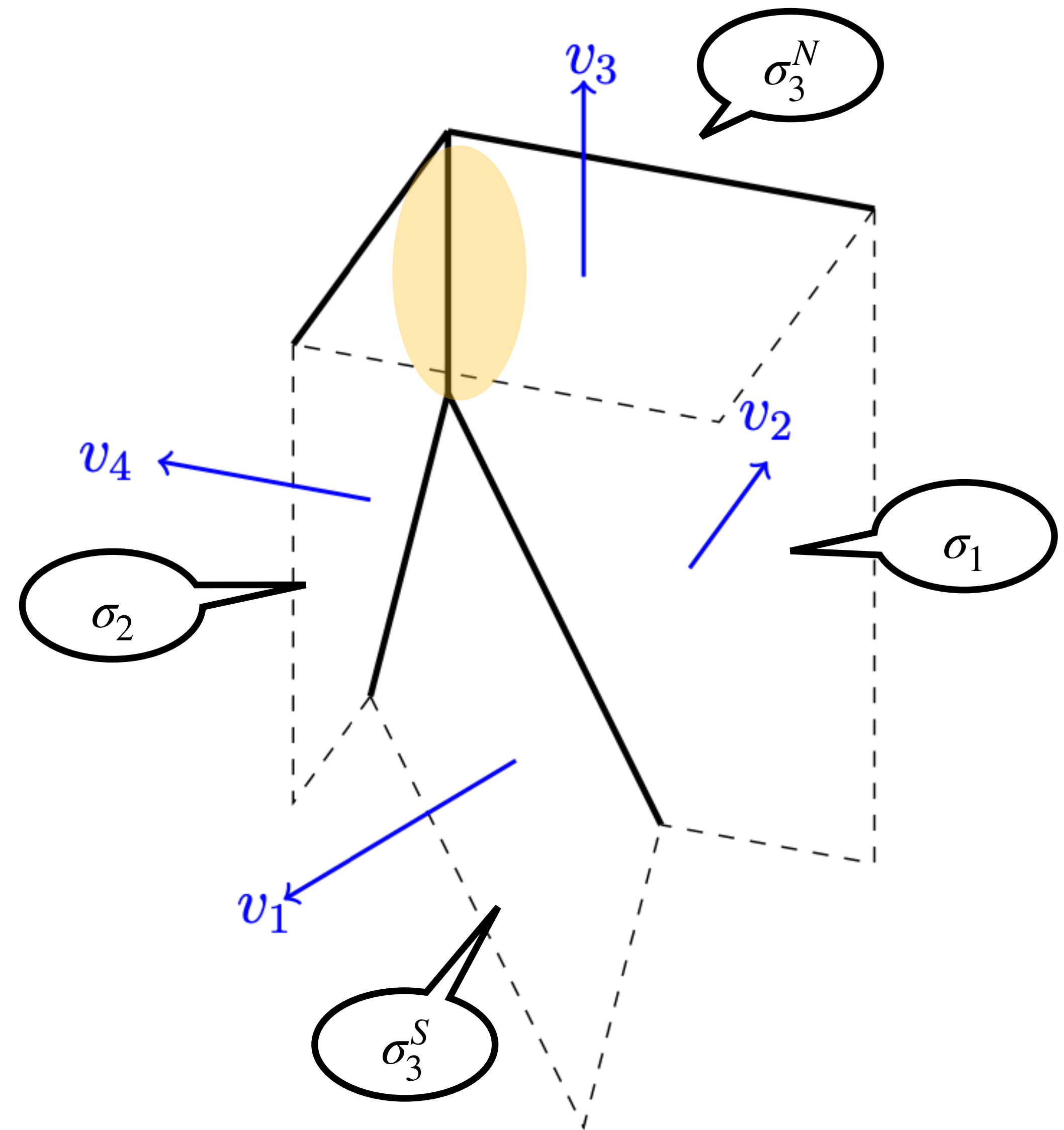
Example 3

$$\mathcal{O}(-p_1) \oplus \mathcal{O}(-p_2) \rightarrow S^2$$

- Chemical potential for angular momentum.
- $\mathcal{O}(-p)$ is fancy for \mathbb{R}^2 plus $d\phi \rightarrow d\phi + A$ with magnetic charge $-p$ for A over S^2 .
- $\xi = b_1 \partial_{\phi_1} + b_2 \partial_{\phi_2} + b \partial_{\psi}$
- Fixed point set at centre of each \mathbb{R}^2 and poles of $S^2 \Rightarrow 2$ fixed points.
- $\int_{S^2} c_1(L_i) = -p_i$
- Weights a bit more difficult now but easy to compute with toric geometry.

Some toric geometry

- Toric diagram for $\mathcal{O}(-p_1) \oplus \mathcal{O}(-p_2) \rightarrow S^2$
- Faces label where a circle shrinks.
- Each face has an associated vector
- Also associated to each face the sign σ .
- The S^2 is in orange.
- v_2, v_4 are the vectors for the $\mathcal{O}(-p_i)$ factors.



$$\begin{aligned}
I = & \frac{F_{S^5}}{27} \left[\sum_{\dim 0} \chi \frac{(\sigma^{(1)}\epsilon_1 + \sigma^{(2)}\epsilon_2 + \sigma^{(3)}\epsilon_3)^3}{\epsilon_1\epsilon_2\epsilon_3} \right. \\
& - \sum_{\dim 2} \frac{\chi(\sigma^{(1)}\epsilon_1 + \sigma^{(2)}\epsilon_2)^2}{\epsilon_1\epsilon_2} \int_{F_2} \left[3c_1(F) + (\sigma^{(1)}\epsilon_1 + \sigma^{(2)}\epsilon_2) \left(\frac{c_1(L_1)}{\epsilon_1} + \frac{c_1(L_2)}{\epsilon_2} \right) \right] \\
& \left. + \sum_{\dim 4} \chi\sigma^{(1)} \int_{F_4} \left[3c_1(F) \wedge c_1(F) + 3\sigma^{(1)}c_1(F) \wedge c_1(L_1) + c_1(L_1) \wedge c_1(L_1) \right] \right]
\end{aligned}$$

$$\{\epsilon_1, \epsilon_2, \epsilon_3\} = \begin{cases} \{b_1, b_2, b_3\} & \text{North pole} \\ \{b_1 + p_1b_3, b_2 + p_2b_3, -b_3\} & \text{South pole} \end{cases}$$

Example 3

$$\mathcal{O}(-p_1) \oplus \mathcal{O}(-p_2) \rightarrow S^2$$

$$I = \frac{F_{S^5}}{27} \sigma^{(1)} \sigma^{(2)} \left(\frac{\sigma_N^{(3)} (\sigma^{(1)} b_1 + \sigma^{(2)} b_2 + \sigma_N^{(3)} b_3)^3}{b_1 b_2 b_3} - \frac{\sigma_S^{(3)} (\sigma^{(1)} (b_1 + p_1 b_3) + \sigma^{(2)} (b_2 + p_2 b_3) - \sigma_S^{(3)} b_3)^3}{(b_1 + p_1 b_3)(b_2 + p_2 b_3) b_3} \right)$$

- Completely new result! No SUGRA solution nor field theory results!
- Has the form of gravitational blocks, like holomorphic blocks from SUSY localisation.
- “Twist” or “anti-twist” depending on whether $\sigma_N^{(3)} = \pm \sigma_S^{(3)}$.
- Reduces to Example 1 for $p_i = 0$, $b_3 = 0$, $g = 2$.

Conclusion

- Equivariant localisation gives a powerful method for computing certain holographic observables.
- Only requires an isometry to apply, for SUSY solutions this is often present (R-sym).
- Applied to Romans SUGRA, recovered old results and found new predictions.
- Hidden subtleties: Existence of actual solutions? Odd-dim works slightly different (need 2 $U(1)$'s). SUSY needed to construct polyforms.
- Many ways to extend: Higher derivative corrections, different matter content, boundaries, exact matches with field theory?

Thank you!

$\mathbb{C}\mathbb{P}^2$ more details

- For ∂_ψ the polyform is:

$$\Phi = \text{vol}(\mathbb{C}\mathbb{P}^2) - \frac{1}{8} \sin^3 \zeta \cos \zeta d\zeta \wedge D\psi + \frac{\sin^4 \zeta + c}{32}$$

- Here c is an arbitrary constant, it will drop out!
- Fixed point has weights: $b_1 = b_2 = \frac{1}{2}$
- Bolt has weights: $b_1 = \frac{1}{2}$.

$$\begin{aligned} \text{Vol} &= \frac{(2\pi)^2}{(1/2)^2} (\Phi_0|_{\zeta=\frac{\pi}{2}}) + \frac{2\pi}{1/2} \left(\int_{S^2} \Phi_2 - \Phi_0|_{\zeta=0} \int_{S^2} c_1(\mathcal{L}) \right) \\ &= \frac{\pi^2}{2} \end{aligned}$$

